

# SHRIVATHSA M S

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## EXPERIENCE

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### **Solvendo - Legal-tech startup** *Software Engineer (Front End)*

Bengaluru, KA  
July 2023 - February 2025

- Worked on an application that streamlined the Indian bankruptcy process for banks, companies, and lawyers, used by institutions such as Canara Bank
- Worked on micro-frontend architecture, user authentication, and configuration management. Technologies used: React, Webpack, Javascript, JWT
- Bootstrapped a new Next.js frontend project for a bankruptcy process with standard coding practices and created standardized, reusable components, reducing dev time by 30%. Technologies used: Next.js, Chakra UI, NextAuth.js
- Worked on a high-performance dashboard application for a blockchain analytics platform. Built rich interactive charts for visualizing time series data and a drag-and-drop interface for blockchain data analysis. The website had 10k MAU at its peak, loaded in under 2 seconds, and a Lighthouse score of 93. Technologies used: Next.js, React-DND, ApexCharts
- Used React DevTools and Lighthouse to diagnose performance issues in React, optimized web page performance, and decreased loading times, reducing FCP by 50%.
- Built a blockchain data processing microservice in Golang to aggregate data from WebSockets and provide REST API endpoints, achieved 8x higher throughput than the previous solution. Technologies used: net/http, REST APIs, WebSockets

### **Indian Institute of Science** *Research Intern*

Bengaluru, KA  
January 2023 - July 2023

- Engineered multi-agent robot systems for agricultural applications, achieving 2x improvement in obstacle avoidance performance through novel algorithms. Technologies used: Python, ROS, EGO Planner
- Developed motion planning algorithms and perception software for UAVs in Python. Technologies used: ROS, Intel Realsense cameras, 2D Lidars
- Integrated UAVs with DJI control software using SDKs to enhance automation capabilities. Technologies used: Python, DJI SDK

### **NewSpace Research & Technologies - UAV & robotics R&D company** *Robotics Engineer*

Bengaluru, KA  
October 2021 - January 2023

- Worked on ROS-based autonomy software for UAVs operating in GPS-denied environments. Technologies used: ROS, Python, Linux, C++
- Optimized robot localization using visual SLAM and LiDAR SLAM algorithms in C++. Technologies used: OpenCV, OpenSLAM, VINS-Stereo/Mono, Ouster Lidars
- Developed UAV simulation tools using python and physics simulation software. Technologies used: Python, Gazebo, Docker, C++

## KEY TECHNICAL SKILLS

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Programming Languages:	HTML, CSS, JavaScript, TypeScript, Go
Frontend Development:	Next.js, React.js, Redux
CSS and UI Libraries:	Material Design, Tailwind CSS, Chakra UI, SASS
Backend Development:	Node.js, Express.js, REST APIs, Microservices, net/http, Docker
Testing:	Jest, Cypress
Databases:	MongoDB
SDLC:	Agile, Git, Jira, Gerrit

## EDUCATION

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**BMS College of Engineering**  
Degree in Mechanical Engineering (BE)  
Electives: AI, Java, Robotics *GPA: 8.75*

Bengaluru, KA  
July 2017 - July 2021

## PROJECTS

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**Aami & The Mangrove** *PIXI.js, TypeScript, npm*

A visual novel built for the web using the PIXI.js library and TypeScript, developed as part of a graduate thesis. Live Demo: <https://aamismangrove.in/>

**WikiTree Browser Extension** *TypeScript, React.js, Chrome Browser Extensions*

A Chrome extension to visualize Wikipedia rabbit holes as interactive trees, built using TypeScript and React. Link: <https://chromewebstore.google.com/detail/wikitree/gmepfbiaaamedihnliggicgbphigbcje?hl=en>